Problems in growth and instabilities of microscopic steps on monocrystalline surfaces: The effects of anisotropic step energy (tension)

# Mikhail Khenner

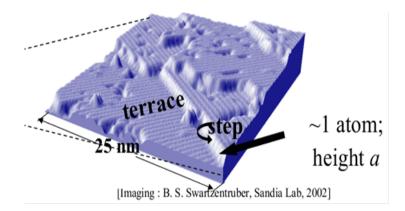
Department of Mathematics, Western Kentucky University

Perm State University, Russia, May 29, 2014

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- Molecular Beam Epitaxy (MBE) is widely used to grow various semiconductor or metal nanostructures (quantum dots, wells, wires, etc.)
- If the substrate on which the crystal grows is a *vicinal (misoriented)* surface, then for metals or semiconductors the growth proceeds in step-flow mode
- Anisotropy of step energy, or tension (a dependence on orientation) has been shown to have a major effect on step morphology (Y. Saito and M. Uwaha, 1996). However, these authors considered weak anisotropy only. In this work, analysis is extended to strong anisotropies.

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step atom corner c(x,y,t)θ kinks  $\mathbf{c}(x,y,t)$ adatoms x 1DN KC Α SC

Introduction to Step Dynamics and Step Instabilities

FIGURE 2. Atomic processes at a step: Attachment (A) and detachment (D) of terrace atoms; step crossing (SC); kink crossing (KC); and one-dimensional nucleation (1DN). As in Fig.1, the upper terrace is shaded.

(From: J. Krug (2004))

Let the step profile be z = h(x, t)

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### Introduction, part III

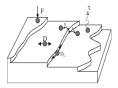


FIG. 4. Summary of various atomic processes on a vicinal surface. Deposition (with a flux F), diffusion (with D as the diffusion constant), desorption (with rate 1/ $\tau$ ), and step attachment or detachment (with rate  $\nu_{\pm}$  from each side) is shown. D<sub>L</sub> represents the line diffusion along the step.

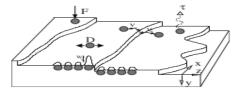


FIG. 10. Schematic view of a vicinal surface. D is the diffusion constant, F is the deposition flux,  $\tau$  is the desorption time, and  $\nu_{\pm}$  are step attachment coefficients from the lower and upper sides, respectively. The potential barrier to jump over the step is denoted as  $W_{s}$ .

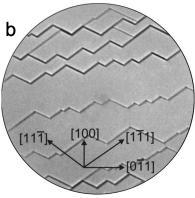
(From: C. Misbah et al. (2010))

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## Example system

MBE growth of refractory metals (niobium, molybdenum, tantalum, tungsten, and rhenium)

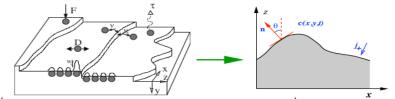
These metals are extraordinarily resistant to heat and wear



(Growth of Nb on Nb(001) substrates; from: M. Ondrejcek et al. (2002))

Notice distinct faceting of steps (light lines: individual steps; dark lines: step bunches)

#### Formulation of one-sided model, part I



(From: C. Misbah et al. (2010); adapted from J. Krug (2004)) Let C: atomic concentration; z = h(x, t): the step profile

$$D\nabla^{2}C - \tau^{-1}C = -F,$$

$$z = h(x, t):$$

$$C = C_{eq} \left[ 1 + \frac{\Omega}{k_{B}\overline{T}} \left\{ \tilde{\beta} - \overline{\delta}(|\alpha|) \left( \frac{\kappa^{2}}{2} + \frac{\kappa_{ss}}{\kappa} \right) \right\} \kappa \right]$$

$$z \to \infty: \quad C = \tau F$$

$$\begin{aligned} \mathbf{v}_{n} &\equiv h_{t} \cos \theta = \Omega D \left( \nabla C_{|z=h(x,t)} \cdot \mathbf{n} \right), \quad \cos \theta = \left( 1 + h_{x}^{2} \right)^{-1/2}, \\ \mathbf{n} &= \left( -h_{x} \cos \theta, \cos \theta \right), \quad \kappa = \frac{-h_{xx}}{\left( 1 + h_{x}^{2} \right)^{3/2}}, \quad \frac{\partial}{\partial s} = \left( \cos \theta \right) \frac{\partial}{\partial x} \end{aligned}$$

$$eta = eta_0(1 + lpha \cos 4 heta), \quad ( ext{good model for fcc-crystals})$$
  
 $ilde{eta} \equiv eta + eta_{ heta heta} = eta_0(1 - 15lpha \cos 4 heta), \quad |lpha| \ge 1/15$ 

 $\alpha$  is the anisotropy strength,  $\overline{\delta}$  is the regularization parameter

$$z = h(x, t): \quad C = C_{eq} \left[ 1 + \frac{\Omega}{k_B \overline{T}} \left\{ \overline{\beta} - \overline{\delta}(|\alpha|) \left( \frac{\kappa^2}{2} + \frac{\kappa_{ss}}{\kappa} \right) \right\} \kappa \right]$$

This b.c. has the highly nonlinear *regularization term*;  $\kappa$  is the step curvature.

Reg. term IS REQUIRED when the step energy  $\beta$  is strongly anisotropic and therefore the step stiffness  $\tilde{\beta} < 0$  for some orientations:  $|\alpha| \ge 1/15$ 

Negativity of  $\tilde{\beta}$  for some  $\theta$  signals that the corner has formed at this orientation on the *equilibrium* crystal shape; in the dynamical situation, this corresponds to the evolution PDE becoming backward parabolic; thus it is ill-posed and unstable to short-wavelength perturbations. Inclusion of the *regularization term* restores well-posedness of the evolution PDE by imposing small radius of curvature at the corners; see A.A. Golovin *et al.* (1998)

# Saito-Uwaha model for weak anisotropy $(\tilde{\beta} > 0 \forall \theta)$ , part l

Longwave perturbations ( $0 < k < k_c$ ) are known to be the most dangerous in the isotropic and weakly anisotropic cases

$$\begin{aligned} x &= \epsilon^{-1/2} X, \ t &= T_0 + \frac{T_2}{\epsilon^2}, \\ h &= \epsilon H_1(X, T_0, T_2) + \epsilon^2 H_2(X, T_0, T_2) + ..., \\ C &= C_0(X, z, T_0, T_2) + \epsilon C_1(X, z, T_0, T_2) + \epsilon^2 C_2(X, z, T_0, T_2)... \end{aligned}$$

Since *h* is assumed  $O(\epsilon)$ , that expansion results in the *weakly nonlinear* evolution PDE for the step profile: the *weakly anisotropic Kuramoto-Sivashinsky equation (waKS)* (Y. Saito and M. Uwaha, 1996)

$$\begin{split} h_t &= -\frac{1}{2} (1 - 8Ah_x^2) h_{xx} - \frac{3}{8} h_{xxxx} + \frac{1}{2} h_x^2, \\ A &= \alpha_{su} \epsilon^2, \quad \alpha_{su} \geq -1/2 \Leftrightarrow |\alpha| \leq 1/15 \Leftrightarrow \tilde{\beta} > 0 \end{split}$$

The PDE we derive is valid for large step deformations and for strong anisotropies, and it is more nonlinear and complicated than the waKS equation

### Saito-Uwaha model for weak anisotropy, part II

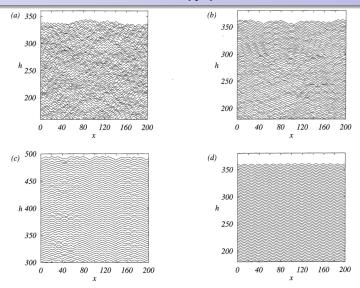


Fig. 1. Time evolution of a step profile with a stiffness anisotropy (a) A = 0 (isotropic), (b) A = 0.2, (c) A = 0.5 and (d) A = 1.0.

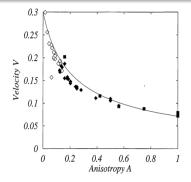
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From: Y. Saito and M. Uwaha (1996)

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#### Saito-Uwaha model for weak anisotropy, part III



From: Y. Saito and M. Uwaha (1996)

Implicit in the derivation is that straight step is long-wave unstable when:

$$F > F_c = F_{eq} \left( 1 + \frac{2\Omega\beta_0}{x_s k_B \overline{T}} \right) > F_{eq}, \text{ since } \beta_0 > 0; \text{ here } x_s = \left( D\tau \right)^{1/2},$$

 $F_{eq} = C_{eq}/\tau$ : the equilibrium flux (sufficient for steady growth of straight step)

Introduce "stretched" variable X, the "fast" time  $T_0$  and the hierarchy of "slow" times  $T_2$ ,  $T_3$ , ...:

$$x = rac{X}{\epsilon}, \quad t = T_0 + rac{T_2}{\epsilon^2} + rac{T_3}{\epsilon^3} + ..., \quad ext{where} \quad \epsilon \ll 1$$

Also expand the concentration in powers of  $\epsilon$ :

$$C = C_0(X, z, T_0, T_2, ...) + \epsilon^2 C_2(X, z, T_0, T_2, ...) + ...$$

Note: h(X,T) is not expanded, meaning large step deformations are allowed: h(x,t) = O(1)

Substitute variables and expansions, collect the like powers of  $\epsilon$  and obtain a sequence of coupled, exactly solvable problems at  $\epsilon^0$ ,  $\epsilon^2$ ,  $\epsilon^4$ ,...

At each order, a problem is an ODE boundary value problem: a 2nd-order ODE in z subject to two b.c.'s, one at  $z \to \infty$  and another at z = h(X)

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- Solve the BVP ODE problems at orders  $\epsilon^0,\;\epsilon^2,\;\epsilon^3,\;\epsilon^4$
- Transfer to the reference frame moving in the z > 0 direction with the speed of straight (unperturbed) step:  $h_{T_0} = \Omega x_s (F F_{eq})$ , where  $F_{eq} = C_{eq}/\tau$  is the flux at the equilibrium, and  $x_s = \sqrt{\tau D}$  is the diffusion length
- Combine the time derivatives:

$$h_t = \epsilon^2 h_{T_2} + \epsilon^3 h_{T_3} + \epsilon^4 h_{T_4}$$

- Introduce the original variable x; this eliminates  $\epsilon^2, \epsilon^3$  and  $\epsilon^4$  from the PDE
- Make the PDE dimensionless by chosing  $x_s$  as the length scale and  $\tau$  as the time scale

Keeping same notations for dimensionless variables:

$$h_{t} = (m_{1} - m_{2}) h_{xx} - m_{3} h_{xxxx} + \frac{m_{1} \mp m_{2}}{2} h_{xx} h_{x}^{2} + m_{1} \left(\frac{3}{2} h_{x}^{4} - h_{x}^{2}\right) \mp m_{2} h_{xxx} h_{x}, \qquad (1)$$

$$m_{1} = \frac{1}{2} (F_{eq} - F) \Omega \tau, \quad m_{2} = \frac{F_{eq} \Omega^{2} \beta_{0} \tau}{k_{B} \overline{T} x_{s}} (15\alpha - 1), \quad m_{3} = \frac{F_{eq} \Omega^{2} \tau \delta(|\alpha|)}{k_{B} \overline{T} x_{s}^{3}} > 0$$

 $m_1$  measures the deviation of the flux from the equilibrium value,  $m_2$  measures the strength of the anisotropy, and  $m_3$  measures the effect of the regularization (corner rounding)

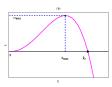
 $\begin{array}{l} +: \ \alpha \geq 1/15 \\ -: \ \alpha \leq -1/15 \quad \mbox{[will choose } + \ \Leftrightarrow \ \alpha \geq 1/15 \ \mbox{in the analysis (stiffness $\widetilde{\beta}$ is minimum in the growth direction $\theta = 0$)]} \end{array}$ 



Our model, part IV: Analysis of the evolution PDE

• Straight step is long-wave unstable, iff

$$m_1 - m_2 < 0 \iff F > F_c = F_{eq} \left( 1 - \frac{2\Omega\beta_0}{x_s k_B \overline{T}} (15\alpha - 1) \right)$$



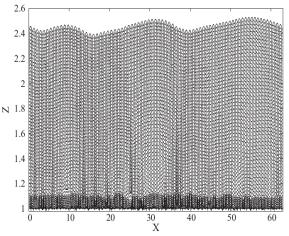
$$k_c = \sqrt{(m_2 - m_1)/m_3}, \quad k_{max} = k_c/\sqrt{2}, \quad \omega_{max} = (m_2 - m_1)^2/4m_3$$

Let  $\alpha \geq 1/15$ , then:

- $F_c < F_{eq}$
- $F_c = 0$  at  $\alpha = \alpha_c = 1/15 + r$ , where  $r = x_s k_B \bar{T}/30\Omega\beta_0$ . Thus at  $\alpha > \alpha_c$  any flux destabilizes the step.  $r \sim 0.01 0.1$
- At F > F<sub>eq</sub> > F<sub>c</sub> the step is unstable and grows (in the frame moving with non-zero speed h<sub>T0</sub>); similar to isotropic and weakly anisotropic cases
- At  $F_c < F < F_{eq}$ , the step is unstable and it grows; (no analog in isotropic and weakly anisotropic cases) ( $h_{T_0} = 0$ )

#### Computational results for strongly anisotropic PDE, part I

Random initial condition  $h(x, 0) = 1 + \text{noise on the large domain } (0 \le x \le 100\lambda_{max})$ , periodic b.c.'s

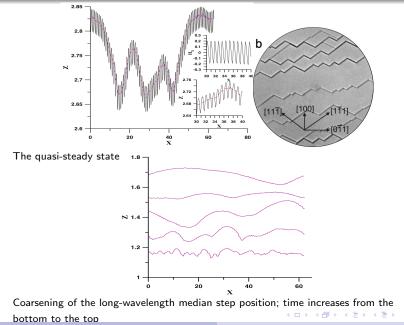


 $\alpha = 1.6, \ F/F_{eq} = 2$ ; time increases from the bottom to the top

A quasi-steady state emerges: Hills and valleys ceased coarsening, but the

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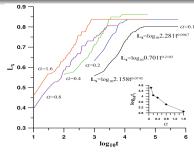
#### Computational results for strongly anisotropic PDE, part II



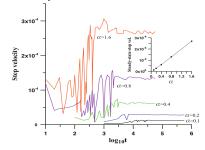
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#### Computational results for strongly anisotropic PDE, part III



Coarsening of the hill-and-valley structure for various  $\alpha$  values



Step speed vs. the time for various  $\alpha$  values

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The effects of anisotropic step energy (tension) ...

- A longwave PDE is formulated for the description of the strongly anisotropic step dynamics within the framework of a one-sided model
- The linear stability of a step depends not only on the strength of the adatoms flux from the terrace to the step, but also on the strength of the step energy anisotropy parameter  $\alpha$
- The critical atomic flux from the terrace that destabilizes the step is *less* than the equilibrium value, and it is even possible to destabilize the step by anisotropy alone by taking  $\alpha$  large enough. That is, *the flux and the anisotropy complement each other in destabilizing the step*.

# THE END

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